



Mooring / Anchoring Systems for Mobile Offshore Rigs







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Introduction

BRÖHL GmbH is one of the oldest marine equipment suppliers in the world. Established in Germany in 1885, BRÖHL specializes in the manufacturing of heavy-duty winches and special machinery for manifold marine applications, as well as in installations for lifting and transferring vessels in shipyards and naval bases worldwide.

BRÖHL provides vast experience with all kind of offshore mooring installations either with rope or chain application.

After decades of refining their expertise Bröhl now defines the world-class standard for designing and building winches.









The product's high quality combined with it's flexible organization and efficient manufacturing processes allow BRÖHL to fulfill individual customer wishes. This in turn has put the company in a solid position in the global market. BRÖHL enjoys a high number of loyal employees. Many of whom have been with the company for the second and third generation sharing in the company's success while preparing it for further prosperity.

Service Centers on all continents ensure support and assistance for the customers on short notice.









Products

Two main types of mooring winches and solutions for the offshore industry are offered:

- Both standardized and customized mooring winches and fairleads for jack-up drilling rigs
- Tailor-made wire rope or chain anchor mooring winches and fairleads for semi-submersible drilling rigs

Other types of winches include those for AHTS- and FPSO vessels, chain systems for production platforms and equipment for pipe laying vessels etc.

All winches are designed and built according to five core requirements:

- > SAFETY
- RELIABILITY
- EASY HANDLING
- LOW MAINTENANCE
- ENVIRONMENT FRIENDLY

In addition, the BRÖHL winch also comes with the following features:

- Designed in compliance with the offshore rules of international classification societies, such as the American Bureau of Shipping (ABS), Det Norske Veritas (DNV) and Lloyd's Register of Shipping (LR), and conforming to ISO 3730 standards (if required)
- Suitable for operation in all kinds of environmental conditions (-10°C to 45°C) relative humidity as high as 95%
- Extremely smooth operations with noise levels to be kept down to as low as 70 dB.

Design

The winches are designed as a compact and robust steel welded construction. Material selection is carefully made according to DIN 17100 General Structural Steel and DIN 17200 Alloyed Steel:

Gear Housing: Steel S355J2G3 or S235JRG2

Foundation : Steel S355J2G3 Rope Drum : Steel S355J2G3

Main Shaft / Axle: Quality Steel C45N (approx. AISI 1042)

Pinion Shafts : Quality Steel 42CrMo4V or C45N (approx. AISI 4140

or AISI 1042 respectively)

Gear Wheel : Quality Steel C45N (approx. AISI 1042)

- The design of the gear wheel is according to the NIEMANN method or other methods as specified by client, such as ISO 6336 or AGMA.
- The gear wheel is made of high alloyed steel, which allows for greater robustness with overload.
- The gear wheels are connected to the shaft by means of fitting keys.
- All shafts are supported by roller bearings.
- The enclosed reduction gear is splash lubricated, and the main gear wheel is grease lubricated. The main gear wheel can be either open or enclosed as required by client's specification.
- The driving motors, attached at the gear housing, are connected to the reduction gear by means of elastic couplings.



















Mooring Winches for Jack-Up Drilling Rigs

Features:

Winch Frame: designed as a bearing housing that supports the drum, with a reduction gearbox integrated into the frame, and supported by a cross beam to ensure a rigid construction

Reduction Gear: completely enclosed design, with highly alloyed spur wheels and pinion shafts running on roller bearings and hard chromium plated replaceable bushes

Rope Drum: designed with LEBUS grooves, machined grooves or flat surface, as applicable.

Main Gear Wheel: grease lubricated and protected by means of a sheet metal cap

Pinion: manually declutchable by means of a dog clutch for free wheeling

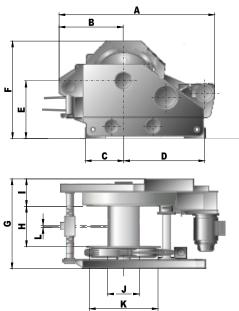
Band Brake: manually operated, with spindle made of stainless steel and high-friction brake lining

Spooling Device: with mechanical direct drive and two vertical guiding rollers; maximum fleet angle of 3.6° to each side

Elastic Motor Coupling: arranged between driving motor and gear wheel; antislip design

Options:

- load measuring device, to be integrated into the winch frame, with 2 stainless steel (AISI 316) load cells suitable for the rope breaking force
- remote controlled hydraulically operated band brake
- remote controlled pneumatically operated band brake
- line-length indication; line-speed indication
- main gear wheel enclosed, in one common housing with reduction gear.



The data provided is for illustration purposes only.

dimensions in mm

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|--|------|------|------|------|------|------|------|------|------|-----|------|----|--|
| | Α | В | С | D | Ε | F | G | Н | - 1 | J | K | L | |
| OMW-250 | 3430 | 1425 | 900 | 1725 | 1270 | 2290 | 2320 | 1080 | 600 | 580 | 1500 | 38 | |
| OMW-300 | 3550 | 1425 | 900 | 1730 | 1270 | 2290 | 2125 | 880 | 600 | 580 | 1500 | 38 | |
| OMW-400 | 3890 | 1480 | 1000 | 1820 | 1320 | 2370 | 2740 | 860 | 1030 | 720 | 1800 | 42 | |
| OMW-500 | 4300 | 1790 | 1000 | 2040 | 1590 | 2930 | 2870 | 960 | 1030 | 720 | 2000 | 45 | |
| OMW-800 | 5030 | 2090 | 1230 | 1800 | 2060 | 3370 | 2900 | 1420 | 650 | 985 | 2300 | 57 | |



Balanced Swivel Fairleads for Jack-Up Drilling Rigs

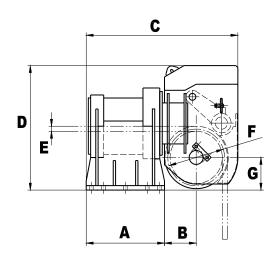
Features:

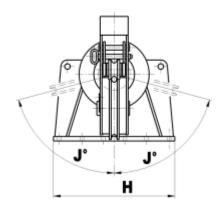
Bearing Pedestal: in robust steel welded construction, designed for rope breaking strength, to be bolted or welded on deck

Swivel Head: with rotary transmission, running on antifriction bearings

Rope Guiding Sheave: made of high strength forged steel, with machined rope grooves, running in anti-friction bearings

Upper Guiding Roller: hinged and suitable for rope insertion, secured by means of a locking bolt





| The d | lata prov | vided is f | | dimensions in mm | | | | | |
|-------|-----------|------------|------|------------------|----|-----|-----|------|-----|
| | Α | В | С | D | Е | F | G | Н | J |
| F14 | 620 | 215 | 1100 | 960 | 38 | 418 | 256 | 1000 | 75° |
| F15 | 680 | 245 | 1240 | 1080 | 42 | 482 | 280 | 1100 | 75° |
| F16 | 740 | 285 | 1385 | 1205 | 45 | 548 | 305 | 1200 | 75° |
| F17 | 840 | 340 | 1630 | 1320 | 54 | 614 | 340 | 1300 | 75° |
| F18 | 890 | 390 | 1800 | 1440 | 57 | 708 | 300 | 1400 | 75° |
| | | | | | | | | | |









Electrical Control

Switch Cabinet - for installation below deck

Protection type IP 54, with all necessary instruments for control of all mooring winches, control transformer 480V or 400V / 230V, standstill heating 230V and ammeter

Options:

- winch-mounted IP56 stainless steel switch cabinet (compact design)
- triple pole-changing
- VFD variable frequency drive

Single Local Control Stand

For control of each mooring winch, protection type IP 56, with seawater resistant housing, complete with the following instruments:

- joystick for winch speed control for hoisting / lowering (at high and low speeds) with back spring pressure for zero positioning
- emergency stop button
- signal lamps
- heating 230V / 20W

Options:

- load indication
- line-length indication
- line-speed indication
- single control stand as portable / pendant type with standpipe and plug-connection

Central Control Panel

Drop-in type to be installed in the bridge panel, complete with the following instruments:

- selector switch for all winches
- signal lamps for all winches
- joystick for hoisting / lowering (at high and low speeds)
- emergency stop button

Options:

- load indication
- line-length indication
- line-speed indication
- central control stand as portable / pendant type



Technical Data

Technical data mechanical part:

| | | OMW-250 | OMW-300 | OMW-400 | OMW-500 | OMW-800 |
|-------------------------------|---------|-------------|-------------|-------------|-------------|-------------|
| Nom. rope pull 1st layer | [kn] | 250 | 300 | 400 | 500 | 800 |
| Rope speed 1st layer | [m/min] | 5,8 / 11,6 | 5,8 / 11,6 | 5,8 / 11,6 | 5,8 / 11,6 | 4/8 |
| Nom. rope pull 10th layer | [kN] | 119 | 142 | 190 | 242 | 275 |
| Rope speed 10th layer | [m/min] | 12,2 / 24,4 | 12,2 / 24,4 | 12,2 / 24,4 | 12,2 / 24,4 | 12,2 / 24,4 |
| Brake holding force 1st layer | [kN] | 600 | 600 | 1000 | 1200 | 2050 |
| Drum ID | [mm] | 580 | 580 | 720 | 720 | 930 |
| Wire size | [mm] | 38 | 38 | 42 | 45 | 57 |
| Drum capacity | [m] | 760 | 760 | 760 | 700 | 1050 |
| Number of layers | | 10 | 10 | 10 | 10 | 10 |
| Total dry weight | [ton] | 9,5 | 10 | 14 | 16 | 28 |

Technical data electrical part:

_X10L1 0L2 0L3

| | | OMW-250 | OMW-300 | OMW-400 | OMW-500 | OMW-800 | |
|----------------------------------|--|--------------|--------------|--------------|--------------|--------------|--|
| Power supply | [V / Hz] | 480 / 60 | 480 / 60 | 480 / 60 | 480 / 60 | 480 / 60 | |
| Power output | [kW] | 27/27 | 32/32 | 46/46 | 58/58 | 64/64 | |
| Protection | [IP] | 56 | 56 | 56 | 56 | 56 | |
| Isolation class (rest. class B) | [kN] | F | F | F | F | F | |
| Motor type | | 3 - phase | |
| Motor surface cooled | | yes | yes | yes | yes | yes | |
| Tropical moisture proof isolatio | n | 100% RH | |
| Operation mode | [min] | S2 - 30 / 30 | |
| Numbers of poles | | 8 - 4 | 8 - 4 | 8 - 4 | 8 - 4 | 8 - 4 | |
| Number of rotation | [rpm] | 875 / 1750 | 875 / 1750 | 875 / 1750 | 875 / 1750 | 875 / 1750 | |
| Spooling protection | | yes | yes | yes | yes | yes | |
| Stand still heating | [220/110 | OV] yes | yes | yes | yes | yes | |
| Electro - magnetic brake | | yes | yes | yes | yes | yes | |
| (fail - safe type) | The data provided is for illustration purposes only. | | | | | | |







Mooring Winches for Semi-Submersible Drilling Rigs

General

The Mooring Winches for semi-submersible rigs in principle consist of a base frame, electric motor, reduction gearbox and a drum or windlass (for wire rope and chain respectively). The basic unit can be extended to include another one, two or three drums or windlasses to create an 8-, 12- or 16-point mooring system.

Existing mooring systems are equipped with shaft couplings for the possibility of a future extension.

Design Criteria

- The winches are designed as a compact and robust steel welded construction.
- All structural parts and components are designed according to the maximum breaking strength of the chain.
- The gear wheel is typically designed according to the NIEMANN method, however other methods are sometimes used if specified by the client, such as ISO 6336 or AGMA.
- All shafts are supported by roller bearings.

Explosion-Proof Design

Ex-proof design for all components necessary to execute emergency release is available as an option.

Regulations

ABS Rules for Building and Classing Mobile Offshore Drilling Units

DNV Rules for Classification of Offshore Drilling and Support Units

DNV Offshore Standard - Position Mooring

Norwegian Maritime Directorate (NMD), Anchoring / Positioning Systems on Mobil Offshore Units

Environmental Design Criteria

The standard Mooring Winches are designed for operation under the following conditions:

Minimum operating temperature: -10°C

Maximum operating temperature: 45°C

Maximum seawater temperature: 35°C

Relative humidity: 95%





Components

The main components of the Mooring Winches are:

Reduction Gear:

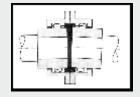
fully enclosed gearbox with spur wheel gears, supported by roller bearings, running in an oil bath, splash lubricated

Pinion:

grease lubricated, driving the main gear wheel.

Transmission Shaft:

with curve-tooth coupling for an easy alignment of the drum or windlass part



Water-Cooled Dynamic Brake:

for drag mode operation during deployment of anchors, spring applied and pneumatically activated, with friction linings of water resistant copper alloy, capable of absorbing a high brake torque at continous operation

Gear Brake:

fail-safe design, pneumatically or hydraulically operated

Gear Shifting:

remote controlled, for operation of winches in low and high gear, with neutral position

Spline Clutch:

remote controlled, for engaging and disengaging of the selected drum or windlass with the winch system

Sling Band Brake:

fail-safe design, pneumatically or hydraulically operated, with non-asbestos woven lining

Option: Two Band Brakes

each band brake with 50% of maximum breaking strength of wire rope or chain in compliance with requirements of ABS MODUT or NMD

Air/Oil Tank:

pressurized air or oil for releasing the band brakes in case of emergency









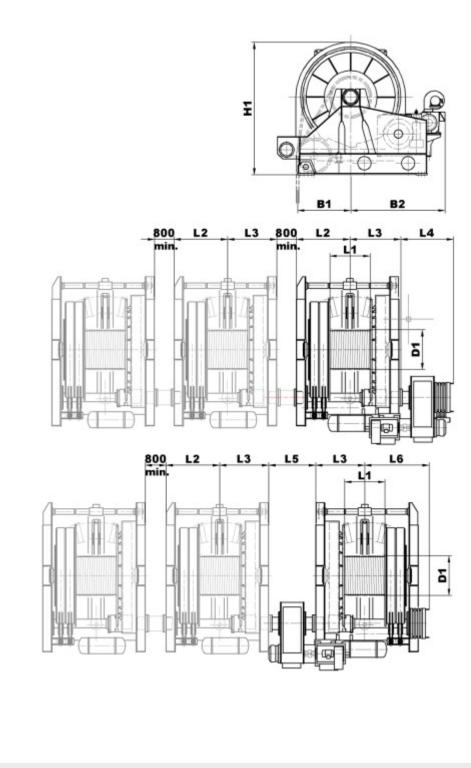








Rope Anchor Mooring Winches



| _ | | RopeSize | D1 | B1 | B2 | H1 | L1 | L2 | L3 | L4 | L5 | L6 |
|---|---------|----------|------|------|------|------|------|------|------|------|------|------|
| | RAMW-25 | 2,5" | 1088 | 1500 | 3170 | 4120 | 1431 | 1870 | 1820 | 1920 | 1590 | 2290 |
| | RAMW-30 | 3" | 1292 | 1710 | 3210 | 4450 | 1439 | 1880 | 1850 | 1920 | 1590 | 2300 |
| | RAMW-35 | 3,5" | 1513 | 2015 | 3580 | 5030 | 1472 | 1900 | 1920 | 2000 | 1640 | 2320 |
| | RAMW-40 | 4" | 1734 | 2215 | 3790 | 5350 | 1687 | 2000 | 2040 | 2040 | 1680 | 2420 |
| | | | | | | | | | | | | |

The data provided is for illustration purposes only.

dimensions in mm



The drum of the Rope Anchor Mooring Winch is equipped with:

Main Gear Wheel:

grease lubricated and protected by means of a sheet metal cap

Rope Drum:

in steel welded construction, with reinforced flanges to withstand the lateral forces of high layer spooling, supported by roller bearings

Option: brake rim with stainless steel surface

LEBUS Grooves:

bolted down split-sleeve type Lebus grooves to ensure a proper spooling of the rope even in high layers

Spooling Device:

a spooling arm with rope sheave operated by a chain driven diamond screw shaft with a manually or automatically operated re-adjustment device

Ratchet Wheel:

with manually activated pawl for fixing the rope drum for maintenance purpose

| Technical Data | | | | |
|----------------------------|--------------------|--------------------|--------------------|--------------------|
| | RAMW-25 | RAMW-30 | RAMW-35 | RAMW-40 |
| Nom. pull 1. step | 700kN x 0-30m/min | 970kN x 0-30m/min | 1370kN x 0-30m/min | 1770kN x 0-30m/min |
| Nom. pull 2. step | 1050kN x 0-20m/min | 1450kN x 0-20m/min | 2050kN x 0-20m/min | 2650kN x 0-20m/min |
| Stalling pull | 770kN / 1160kN | 1070kN / 1600kN | 1500kN / 2260kN | 1950kN / 2920kN |
| Rope length | 4900 ft | 4900 ft | 4900 ft | 4900 ft |
| Layer | 13 | 13 | 12 | 10 |
| Power output | 415 kW | 570 kW | 810 kW | 1050 kW |
| Brake holding force | 3320 kN | 4680 kN | 6570 kN | 8440 kN |
| Pay-out speed (dyn. brake) | 100m/min at 670kN | 100m/min at 1000kN | 100m/min at 1000kN | 100m/min at 1000kN |

The data provided is for illustration purposes only.

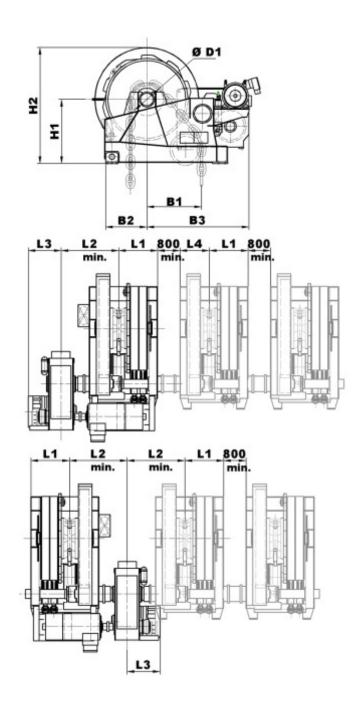








Chain Anchor Mooring Winches



| | ChainSize | D1 | L1 | L2 | L3 | L4 | B1 | B2 | В3 | H1 | H2 |
|---------|-----------|------|------|------|------|------|------|------|------|------|------|
| CAMW-30 | 3" | 991 | 1230 | 1900 | 1150 | 950 | 1800 | 1380 | 3280 | 2240 | 3850 |
| CAMW-35 | 3,5" | 1170 | 1390 | 2065 | 1250 | 1055 | 1950 | 1475 | 3655 | 2300 | 4160 |
| CAMW-40 | 4" | 1326 | 1550 | 2230 | 1300 | 1100 | 2100 | 1620 | 3990 | 2380 | 4300 |

The data provided is for illustration purposes only.

dimensions in mm



The windlass of the Chain Anchor Mooring Winch is equipped with:

Main Gear Wheel:

grease lubricated and protected by means of a sheet metal cap

Cable Lifter:

with 5 snugs, suitable to accommodate the kenter shackle, in high grade cast material, supported by roller bearings

Option: brake rim with stainless steel surface

Chain Stripper:

to prevent the chain from getting stuck in the cable lifter

Sheave:

to ensure a proper guiding of the chain down to the chain locker

Ratchet Wheel:

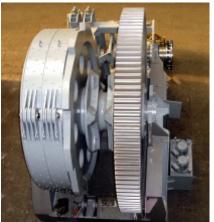
with manually activated pawl for fixing the cable lifter for maintenance purpose

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| - 1 | Гес | nn. | 100 | 101 | 2 |
| - 1 | ᆫ | | ıvaı | aı | a. |

| | CAMW-30 | CAMW-35 | CAMW-40 |
|----------------------------|--------------------|--------------------|--------------------|
| Nominal pull 1.step | 980kN x 0-18m/min | 1350kN x 0-18m/min | 1680 x 0-18m/minkN |
| Nominal pull 2. step | 1955kN x 0-9m/min | 2700kN x 0-9m/min | 3365kN x 0-9m/min |
| Stalling pull | 2150 kN | 2970 kN | 3700 kN |
| Brake holding force | 6010 kN | 8190 kN | 10240 kN |
| Power output | 350 kW | 480 kW | 600 kW |
| Pay-out speed (dyn. brake) | 100m/min at 1000kN | 100m/min at 1000kN | 100m/min at 1000kN |

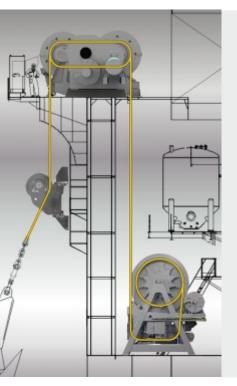
The data provided is for illustration purposes only.











Traction and Storage Winch Systems

In Traction and Storage Winch Systems a Double Drum Traction Winch on deck operates together with a corresponding Storage Winch generally placed at the bottom of the column.

The rope will be wrapped around the grooved drum pair of the Traction Winch in a single layer.

The rope is not firmly clamped on the drum but is held by friction only.

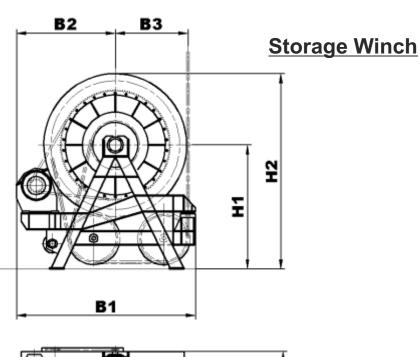
The complete rope length will be reeled on the drum of the Storage Winch.

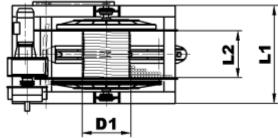
There is a constant pulling force over the complete rope length without any losses, unlike conventional wire rope winches with multi-layer drums.

The pulling force of the Storage Winch will be controlled by signals given by load cells in the Traction Winch, thus ensuring a sufficient pre-tension at any time.



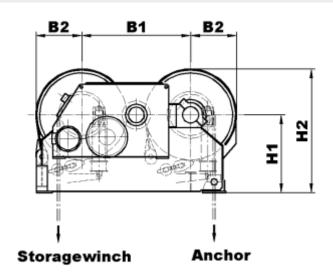


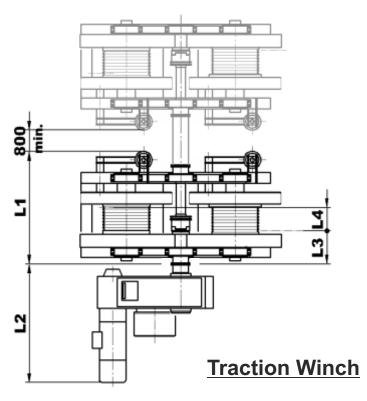




| | RopeSize | RopeLength | Layer | D1 | B1 | B2 | В3 | L1 | L2 | H1 | H2 |
|-------|----------|------------|-------|------|------|------|------|------|------|------|------|
| SW-30 | 3" | 4900 ft | 15 | 1296 | 4760 | 2630 | 1930 | 2600 | 1240 | 3300 | 5200 |
| SW-35 | 3,5" | 4900 ft | 15 | 1530 | 5460 | 2990 | 2260 | 2660 | 1250 | 3590 | 5800 |
| SW-40 | 4" | 4900 ft | 14 | 1734 | 5820 | 3090 | 2460 | 2780 | 1340 | 3950 | 6350 |













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| | RopeSize | D1 | B1 | B2 | L1 | L2 | L3 | L4 | H1 | H2 |
|-------|----------|------|------|------|------|------|------|-----|------|------|
| TW-30 | 3" | 1300 | 3000 | 1270 | 3110 | 3280 | 920 | 640 | 2150 | 3420 |
| TW-35 | 3,5" | 1530 | 3550 | 1500 | 3250 | 3310 | 1080 | 750 | 2450 | 3950 |
| TW-40 | 4" | 1734 | 4050 | 1750 | 3430 | 3360 | 1250 | 850 | 2820 | 4570 |

Technical Data

| | TW-30 | TW-35 | TW-40 |
|---------------------------|---------------------|--------------------|--------------------|
| Nom. pull 1. step | 970kNx30m/min | 1370kNx30m/min | 1770kNx30m/min |
| Nom. pull 2. step | 1450kNx20m/min | 2050kNx20m/min | 2650kNx20m/min |
| Stalling pull | 1070kN / 1600kN | 1500kN / 2260kN | 1950kN / 2920kN |
| Brake holding force | 4680kN | 6570kN | 8440kN |
| Pay-out speed (dyn. brake |)100m/min at 1000kN | 100m/min at 1000kN | 100m/min at 1000kN |

The data provided is for illustration purposes only.



Drives

The winches are driven either by a squirrel-cage AC motor or by a shunt-wound DC motor in 4-quadrant operation:

AC Motor

Three-phase squirrel cage motor, construction type IM B3, IP 56, S2-60 min., insulation class F, with temperature sensors, axially preloaded roller bearings and anti-condensation heating

DC Motor

e.g. GE 752 high torque DC drilling motor, with pressurized connection box, space heater, pressure sensor and blower assembly

The motors will be controlled by a variable frequency drive (VFD) or a silicon controlled rectifier (SCR).

VFD and SCR can be part of the winch control system or supplied by any suitable external system.

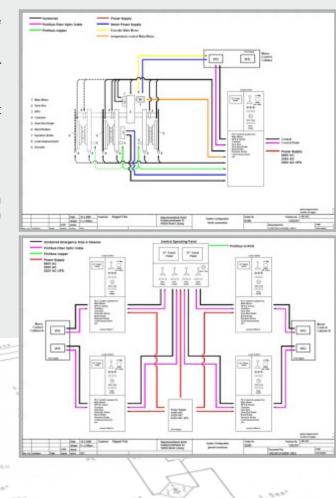
Both VFD and SCR systems allow the winch to be operated at different speeds during operation.

High Pressure Hydraulic Drive

Alternatively - in the range of up to 600 kW performance - a high pressure hydraulic drive system is available, with each winch drive consisting of:

2x motors, axial piston type, system pressure 250 bar

1 x closed circuit Hydraulic Power and Control Unit (HPU) with variable displacement pumps of axial piston type





Control

The control is a PLC based system with a high degree of automation. Operations such as shifting to different gears as well as operating the different clutches and band brakes are automatically carried out by the control system.

Clear text displays will be supplied for the local control panels as well as for the central control panel. Indicating lights will inform the operator of the status and availability of the system. The automatic control system ensures that the possibility of wrong or unsafe operations is reduced to a minimum.

Features of automatic control system:

- Monitoring of motor current and motor temperature, air pressure resp. oil pressure and oil level in HPU as well as temperature of cooling water of dynamic brakes
- Measuring of tension by load cells based on RSG technology
- Measuring of speed and length of wire rope or chain by digital encoders
- Local control panel with 10" touch screen con-taining all of the following for the operation of the winch system:
 - Main switch ON/OFF
 - Tension indicator
 - Length indicator
 - Speed indicator
 - Winch speed control joystick
 - Winch dynamic brake control regulator
 - Emergency brake release button
 - Emergency stop button
 - Status and alarm lamp
- Central control panel with 15" touch screens with joysticks, push buttons and indicating lights for the operation of the selected winch system:
 - Selector switch for drum or windlass on selected winch system
 - Selector switch for gearstep (1 or 2) or drag mode (3)
 - Emergency brake release button for all winches
 - Emergency stop button for all winches
 - Status and alarm lamps

Option:

local operator's cabin with heating, air condition, wipers, safety rail and access board at the outer perimeter





















Chain Jacking Systems

Chain Jacking Systems are an alternative to wire rope or chain anchor ainches whenever very high pulling forces are required or when there are space restrictions on the deck.

Chains with very big diameters can be paid-in and paid-out by lifting and lowering of hydraulic jacks in a step-by-step operation.

Features of the Chain Jacking System:

Skid Frame: in steel welded construction

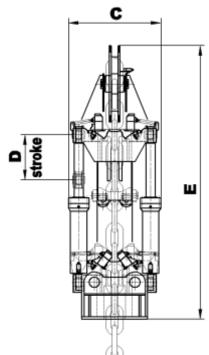
Stationary Chain Stopper: double flap-type, hydraulically operated with integrated load cell

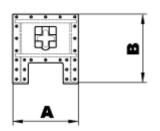
Travelling Chain Stopper: double flap-type, hydraulically operated

Lifting Jacks: with ceramic coated piston rods and pivoting bearings made of stainless steel

Guiding Sheave (Turn-Down Sheave): with 5 snugs and measuring device for chain length

Hydraulic Power and Control Unit (HPU): with oil tank, 2 variable displacement pumps of axial piston type, 2 AC motors and 2 servo pumps, valve block, switchgear cabinet, monitoring and alarm equipment





| Cha | ainSize | Α | В | С | D | Е |
|-------|---------|------|------|------|------|------|
| CJ-30 | 3" | 1000 | 1200 | 1400 | 780 | 4750 |
| CJ-40 | 4" | 1280 | 1350 | 1800 | 1025 | 5550 |
| CJ-50 | 5" | 1625 | 1715 | 2290 | 1300 | 7050 |

dimensions in mm

| | CJ-30 | CJ-40 | CJ-50 | |
|----------------|---------|---------|----------|--|
| Nom. pull | 1700 kN | 2500 kN | 3350 kN | |
| Speed in/out | 22 m/h | 22 m/h | 22 m/h | |
| Max. pull | 2000 kN | 3000 kN | 4000 kN | |
| Static force | 6010 kN | 8965 kN | 14980 kN | |
| Cylinder bore | 220 mm | 260 mm | 300 mm | |
| Hydr. pressure | 300 bar | 300 bar | 300 bar | |
| | | | | |

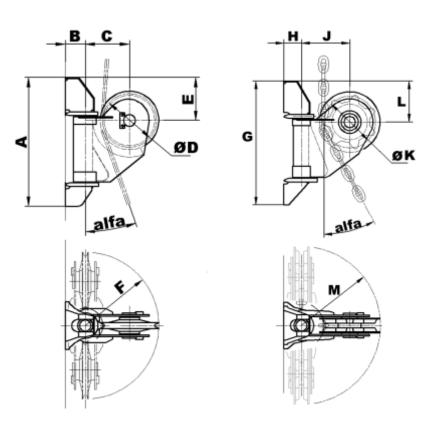


Rope and Chain Fairleads

The Rope and Chain Fairleads are column-mounted steel welded constructions made of S355J2+N material. Each fairlead consists of upper and lower brackets, side plates, axles and sheaves (for wire rope) or cable lifter (for chain).

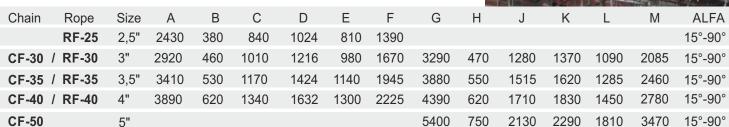
Features of the Rope and Chain Fairleads:

- Designed for maximum breaking strength of wire rope resp. chain
- For operation above and under water
- Swivelling 90° either side of centre
- Sheave up to 90° arc of contact of the wire rope
- Cable lifter with 7 snugs (for chain)
- Self-lubricated bushings
- Axles with stainless steel surface made of AISI / SAE 316 material
- Option: axles supported by spherical roller bearings
- Option: wire or chain running through trunnion (compact design)





dimensions in mm











Reference List

Jack-Up Drilling Rigs

| HULLN | o. OWNER | VESSEL NAME | HULL No | . OWNER | VESSEL NAME | HULL No | . OWNER | VESSEL NAME |
|--------|---------------------|-------------------|---------|-------------------|----------------|---------|--------------|-------------|
| KF B26 | NDC | Al-Hail | KF B324 | UMW | UMW Naga 4 | KF B359 | Ensco | Ensco 110 |
| KF B26 | 3 DDI | Deep Driller 2 | KF B325 | Arab Drilling | Arab Drill 50 | KF B360 | Grupo R | Paraiso I |
| KF B26 | 7 DDI | Deep Driller 3 | KF B326 | Transocean | Siam Driller | KF B361 | Grupo R | Paraiso II |
| KF B27 | 1 DDI | Deep Driller 5 | KF B327 | Transocean | Andaman | KF B363 | PetroVietnam | |
| KF B28 | 4 DDI | Deep Driller 6 | KF B328 | Oro Negro | Primus | KF B376 | UMW | |
| KF B28 | 9 DDI | Deep Driller 8 | KF B329 | Ensco | Ensco 120 | M- 1123 | | |
| KF B26 | 9 Awilco | WilCraft | KF B330 | Ensco | Ensco 121 | KF B364 | Transocean | |
| KF B28 | 5 Awilco | WilBoss | KF B331 | Maersk | Intrepid | KF B365 | Transocean | |
| KF B29 | 3 Awilco | WilStrike | KF B332 | Maersk | Interceptor | KF B366 | Transocean | |
| KF B27 | 3 Maersk | Maersk Resilient | KF B333 | JDC | Hakuryu 11 | KF B367 | Transocean | |
| KF B27 | 4 Maersk | Maersk Resolute | KF B334 | Vision Drilling | Dynamic Vision | KF B368 | Transocean | |
| KF B27 | 5 Maersk | Maersk Resolve | KF B335 | Transocean | Ao Thai | KF B369 | Ensco | Ensco 123 |
| KF B27 | 6 Maersk | Maersk Reache | KF B336 | Oro Negro | Laurus | KF B371 | Fecon | |
| KF B27 | 7 Seadrill | West Atlas | KF B337 | CP Latinas | La Santa Maria | KF B372 | Fecon | |
| KF B29 | 1 Seadrill | West Arial | KF B338 | CP Latinas | La Covadonga | KF B373 | Fecon | |
| KF B31 | I Seadrill | West Callisto | KF B339 | Arab Drilling | Arab Drill 60 | KF B374 | Kencana | SKD Raiqa |
| KF B31 | 2 Seadrill | West Juno | KF B340 | UMW | UMW Naga 5 | | | |
| KF B28 | 3 GDI | Al-Zubarah | KF B341 | GDI | | | | |
| KF B29 |) Jindal | Discovery I | KF B342 | GDI | Dukhan | | | |
| KF B29 | 2 Jindal | Virtue I | | Asia Offshore | AOD III | | | |
| KF B29 | 4 Great Eastern | Greatdrill Chetna | KF B346 | Ensco | Ensco 122 | | | |
| KF B29 | 7 Great Eastern | Greatdrill Chitra | KF B347 | | | | | |
| |) Rowan | Rowan Viking | | Clear Water | | | | |
| KF B30 | 1 Rowan | Rowan Stavanger | | Clear Water | | | | |
| | Rowan | Rowan Norway | | Star Drilling | | | | |
| KF B31 | 7 Workfox | Seafox 5 | KF B354 | Grupo R | Cantarell 1 | | | |
| | 9 Chernomorneftegaz | | KF B355 | The second second | Cantarell 2 | | | |
| | Asia Offshore | AODI | KF B356 | | Cantarell 3 | | | |
| KF B32 | 1 Asia Offshore | AOD II | KF B357 | Grupo R | Cantarell 4 | | | |

Semi-Submersible Drilling Rigs

| KF B280 | Maersk | Maersk Developer | KF B288 | Transocean | DD III | |
|---------|--------|-------------------|---------|----------------|--|------|
| KF B281 | Maersk | Maersk Discoverer | KF B296 | Queiroz Galvao | Gold Star | r |
| KF B295 | Maersk | Maersk Deliverer | KF B309 | Queiroz Galvao | Alpha Sta | ar |
| KF B286 | Ensco | Ensco 8500 | KF B316 | PetroVietnam | PV Drillin | ng V |
| KF B287 | Ensco | Ensco 8501 | | | | |
| KF B298 | Ensco | Ensco 8502 | | | | |
| KF B303 | Ensco | Ensco 8503 | | | | |
| KF B308 | Ensco | Ensco 8504 | | | | |
| KF B310 | Ensco | Ensco 8505 | | | 68 | |
| KF B315 | Ensco | Ensco 8506 | | 1 | ार्थालां व | 150 |
| | | | | | 100 Pt 10 | 100 |

Semi-Submersible Accommodation Vessels

| KF B261 | Prosafe | Consafe Concordia | KF B343 | Floatel | Floatel Victory |
|---------|---------|-------------------|---------|---------|-------------------|
| KF B302 | Floatel | Floatel Superior | KF B348 | Floatel | Floatel Endurance |
| KF B307 | Floatel | Floatel Reliance | KF B362 | Floatel | Floatel Triumph |

Floating Drilling, Production, Storage and Offloading Vessels

KS 379 Prosafe Azurite

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